



Sharif University of Technology
Department of Mechanical Engineering

Connectionist Temporal Classification (CTC)

Social Robotics

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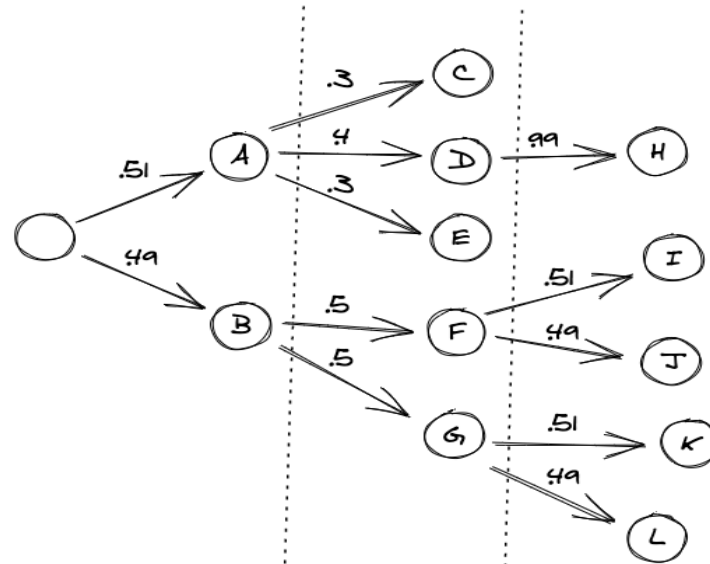
- **TensorFlow**
- **Keras**
- **PyTorch**

For training

- `tf.nn.ctc_loss(labels,` Tensor of shape [batch_size, max_label_seq_length]
`logits,` Tensor of shape [frames, batch_size, num_labels]
`label_length,` Tensor of shape [batch_size]
`logit_length,` Tensor of shape [batch_size]
`logits_time_major,` If True (default), [frames, batch_size, num_labels]
If False, shape is [batch_size, frames, num_labels]
`unique,` Unique label indices as computed by `ctc_unique_labels(labels)`
`blank_index)` Set the class index to use for the blank label.
Default = 0

`loss`: A 1-D float Tensor of shape [batch_size], containing negative log probabilities.

Beam search and greedy decoder



Greedy: A

Beam: A, B

Greedy: AD

Beam: BF, BG

Greedy: ADH

Beam: BFI, BGK

For inference

- `tf.nn.ctc_beam_search_decoder(`

 inputs, 3-D float Tensor, size [max_time, batch_size, num_classes]

 sequence_length, 1-D int32 vector containing sequence lengths[batch_size]

 beam_width, An int scalar ≥ 0 (beam search beam width)

 top_path) An int scalar ≥ 0 , $\leq$ beam_width (controls output size)

Returns: A tuple (decoded, log_probabilities)

For inference

- `tf.nn.ctc_greedy_decoder(`

 `inputs,` 3-D float Tensor, size `[max_time, batch_size, num_classes]`

 `sequence_length,` 1-D int32 vector containing sequence lengths`[batch_size]`

 `merge_repeated,` `Default: True`

 `blank_index)` `(Optional). Default: num_classes - 1`

Returns: A tuple (decoded, neg_sum_logits)

K Keras

for training

- `ctc_loss = tf.keras.losses.CTC (`
 `reduction='sum_over_batch_size',`
 `name='sparse_categorical_crossentropy')`

```
loss = ctc_loss ( y_true, y_pred )
```

for inference

- `tf.keras.ops.ctc_decode( inputs,`
 `"greedy" or`
 `"beam_search"`
 `sequence_lengths,`
 `strategy,`
 `beam_width,`
 `top_paths,`
 `merge_repeated)`

PyTorch

For training

- `Torch.nn.CTCLoss(blank, reduction, zeros_infinity)`

```
ctc_loss = nn.CTCLoss()
```

```
loss = ctc_loss(input,          3-D float Tensor, size [max_time, batch_size, num_classes]  
                target,        Tensor of shape [batch_size, max_label_seq_length]  
                input_lengths,  Tensor of shape [batch_size]  
                target_lengths) Tensor of shape [batch_size]
```

Output: scalar if reduction is 'mean' (default) or 'sum'. If reduction is 'none', output shape will be [batch_size]